

6.8 Orthonormal Bases

DEF → p.306

A set of vectors $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ in R^n is said to be **orthogonal** if

(a) $\vec{v}_i \cdot \vec{v}_j = 0$ for all $i \neq j$.

S is said to be **orthonormal** if in addition to the condition (a), it also satisfies

(b) $\vec{v}_i \cdot \vec{v}_i = 1$ for all $i = 1, \dots, k$.

EXAMPLE 1 $S = \{\vec{i}, \vec{j}, \vec{k}\}$ is an orthonormal

set in R^3 , since

(a) $\vec{i} \cdot \vec{j} = \vec{j} \cdot \vec{k} = \vec{i} \cdot \vec{k} = 0$, and

(b) $\vec{i} \cdot \vec{i} = \vec{j} \cdot \vec{j} = \vec{k} \cdot \vec{k} = 1$.

EXAMPLE 2 $S = \{(1, -1, 2, 3), (-1, 1, 1, 0)\}$ is an

orthogonal set in R^4 , since

(a) $(1, -1, 2, 3) \cdot (-1, 1, 1, 0) = 0$.

However, S is not orthonormal since (b) does not hold: $(1, -1, 2, 3) \cdot (1, -1, 2, 3) = 15 \neq 1$.

TH 6.16 $\rightarrow$ p.307

Every orthogonal set of nonzero vectors is linearly independent.

DEF $\rightarrow$ p.307

An orthogonal (orthonormal) set of vectors in a vector space V that forms a basis for V is called an **orthogonal (orthonormal) basis** for V .

TH 6.17 → p.308

If $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is an orthonormal basis for R^n then for every vector $\vec{v}$ in R^n :

$$\vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$

where $c_i = \vec{v} \cdot \vec{v}_i$ for all i .

Proof

Since S is a basis, then we can write

$$\vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$

Multiplying both sides by $\vec{v}_i$ yields

$$\vec{v} \cdot \vec{v}_i = c_1(\vec{v}_1 \cdot \vec{v}_i) + c_2(\vec{v}_2 \cdot \vec{v}_i) + \dots + c_n(\vec{v}_n \cdot \vec{v}_i)$$

Since S is orthogonal then only the i -th term on the right hand side can be nonzero:

$$\vec{v} \cdot \vec{v}_i = c_i(\vec{v}_i \cdot \vec{v}_i)$$

Because S is orthonormal,

$$c_i = \vec{v} \cdot \vec{v}_i$$

TH 6.18 Gram-Schmidt Process → p.308

Let W be a nonzero subspace of R^n with a basis $S = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k\}$. Then an orthonormal basis T for W can be determined by the following process:

(1) Determine an orthogonal basis for W :

$$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$$

$$\vec{v}_1 = \vec{u}_1$$

$$\vec{v}_2 = \vec{u}_2 - \frac{\vec{u}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1$$

$$\vdots$$

$$\vec{v}_i = \vec{u}_i - \frac{\vec{u}_i \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \dots - \frac{\vec{u}_i \cdot \vec{v}_{i-1}}{\vec{v}_{i-1} \cdot \vec{v}_{i-1}} \vec{v}_{i-1}$$

$$\vdots$$

(2) Determine $T = \{\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k\}$, an orthonormal basis for W by normalizing each of the orthogonal vectors $\vec{v}_i$:

$$\vec{w}_i = \frac{\vec{v}_i}{\|\vec{v}_i\|} \text{ for all } i$$

EXAMPLE 3

Apply the Gram-Schmidt Process to the set
 $\{ \underbrace{(1, 1, 0)}_{\vec{u}_1}, \underbrace{(1, 2, 0)}_{\vec{u}_2}, \underbrace{(0, 1, 2)}_{\vec{u}_3} \}.$

$$\begin{aligned}
 (1) \quad \vec{v}_1 &= \vec{u}_1 = (1, 1, 0) \\
 \vec{v}_2 &= \vec{u}_2 - \frac{\vec{u}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 \\
 &= (1, 2, 0) - \frac{(1, 2, 0) \cdot (1, 1, 0)}{(1, 1, 0) \cdot (1, 1, 0)} (1, 1, 0) \\
 &= (1, 2, 0) - \frac{3}{2} (1, 1, 0) \\
 &= \left(-\frac{1}{2}, \frac{1}{2}, 0\right) \\
 \vec{v}_3 &= \vec{u}_3 - \frac{\vec{u}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{u}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 \\
 &= (0, 1, 2) - \frac{(0, 1, 2) \cdot (1, 1, 0)}{(1, 1, 0) \cdot (1, 1, 0)} (1, 1, 0) \\
 &\quad - \frac{(0, 1, 2) \cdot \left(-\frac{1}{2}, \frac{1}{2}, 0\right)}{\left(-\frac{1}{2}, \frac{1}{2}, 0\right) \cdot \left(-\frac{1}{2}, \frac{1}{2}, 0\right)} \left(-\frac{1}{2}, \frac{1}{2}, 0\right) \\
 &= (0, 1, 2) - \frac{1}{2} (1, 1, 0) - \left(-\frac{1}{2}, \frac{1}{2}, 0\right) \\
 &= (0, 0, 2).
 \end{aligned}$$

$$\begin{aligned}
(2) \quad \vec{w}_1 &= \frac{\vec{v}_1}{\|\vec{v}_1\|} = \frac{(1,1,0)}{\sqrt{1+1+0}} \\
&= \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0\right) = \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0\right) \\
\vec{w}_2 &= \frac{\vec{v}_2}{\|\vec{v}_2\|} = \frac{(-\frac{1}{2}, \frac{1}{2}, 0)}{\sqrt{\frac{1}{4} + \frac{1}{4} + 0}} \\
&= \sqrt{2} \left(-\frac{1}{2}, \frac{1}{2}, 0\right) = \left(-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0\right) \\
\vec{w}_3 &= \frac{\vec{v}_3}{\|\vec{v}_3\|} = \frac{(0,0,2)}{\sqrt{0+0+4}} = (0,0,1)
\end{aligned}$$

We obtained the orthonormal basis

$$T = \left\{ \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0\right), \left(-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0\right), (0,0,1) \right\}.$$

EXAMPLE 4 Verify **TH 6.17** for

$\vec{v} = (2, -1, 3)$ and the orthonormal basis T obtained above.

$$c_1 = \vec{v} \cdot \vec{w}_1 = (2, -1, 3) \cdot \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0\right) = \frac{\sqrt{2}}{2}$$

$$c_2 = \vec{v} \cdot \vec{w}_2 = (2, -1, 3) \cdot \left(\frac{-\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0\right) = \frac{-3\sqrt{2}}{2}$$

$$c_3 = \vec{v} \cdot \vec{w}_3 = (2, -1, 3) \cdot (0, 0, 1) = 3$$

Verify:

$$\begin{aligned} & \frac{\sqrt{2}}{2} \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0\right) - \frac{3\sqrt{2}}{2} \left(\frac{-\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0\right) + 3(0, 0, 1) \\ &= \left(\frac{1}{2}, \frac{1}{2}, 0\right) + \left(\frac{3}{2}, \frac{-3}{2}, 0\right) + (0, 0, 3) \\ &= (2, -1, 3) \checkmark \end{aligned}$$