

4.3 Intro to Linear Transformations

DEF Linear Transformation ($\rightarrow$ p. 201)

A function $L : R^n \rightarrow R^m$ such that

- (a) $L(\vec{u} + \vec{v}) = L(\vec{u}) + L(\vec{v})$, for every $\vec{u}$ and $\vec{v}$ in R^n .
- (b) $L(c\vec{u}) = cL(\vec{u})$, for every vector $\vec{u}$ in R^n and every scalar c .

$L(\vec{u})$ is the **image** of $\vec{u}$

Range of L - set of all images of vectors in R^n .

EXAMPLE 1

Consider $L : R^2 \rightarrow R^2$ defined by $L(x, y) = (x, 0)$.
Check:

$$\begin{aligned} \text{(a)} \quad LHS &= L(\vec{u} + \vec{v}) \\ &= L((x, y) + (x', y')) \\ &= L(x + x', y + y') \\ &= (x + x', 0) \\ RHS &= L(\vec{u}) + L(\vec{v}) \\ &= L(x, y) + L(x', y') \\ &= (x, 0) + (x', 0) \end{aligned}$$

Therefore, $LHS = RHS$ for every $\vec{u}$ and $\vec{v}$ in R^n .

$$\begin{aligned} \text{(b)} \quad LHS &= L(c\vec{u}) = L(cx, cy) = (cx, 0) \\ RHS &= cL(\vec{u}) = c(x, 0) \end{aligned}$$

Therefore, $LHS = RHS$ for every vector $\vec{u}$ in R^n and every scalar c .

Conclude: L is a linear transformation.

Projection of the entire R^2 plane onto the x -axis.
(also $\rightarrow$ Example 1 p.201)

EXAMPLE 2

Consider $L : R^2 \rightarrow R^3$ defined by

$$L\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} x + y \\ 1 \\ x - y \end{bmatrix}. \text{ Check:}$$

$$(a) \text{ LHS} = L(\vec{u} + \vec{v})$$

$$= L\left(\begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} x' \\ y' \end{bmatrix}\right)$$

$$= L\left(\begin{bmatrix} x + x' \\ y + y' \end{bmatrix}\right)$$

$$= \begin{bmatrix} x + x' + y + y' \\ 1 \\ x + x' - (y + y') \end{bmatrix}$$

$$\begin{aligned}
RHS &= L(\vec{u}) + L(\vec{v}) = \\
&= L\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) + L\left(\begin{bmatrix} x' \\ y' \end{bmatrix}\right) \\
&= \begin{bmatrix} x + y \\ 1 \\ x - y \end{bmatrix} + \begin{bmatrix} x' + y' \\ 1 \\ x' - y' \end{bmatrix} \\
&= \begin{bmatrix} x + y + x' + y' \\ 2 \\ x - y + x' - y' \end{bmatrix}
\end{aligned}$$

$LHS \neq RHS$ therefore L is not a linear transformation.

(→ Example 2 p. 202)

Other types of linear transformations: dilation, contraction, reflection, rotation. (→ Examples in the text)

→ Theorems 4.6, 4.7, 4.8